

Stain Busters



Goal: Fast, objective, and non-invasive AI-based method for automatic stain detection.

Why Stain Detection?

Abstract: AI-based method that uses simple mobile phone photos to quickly identify harmful stains on historical documents and help archivists decide which items need professional restoration.

- *Fungi, bacteria, insects and foxing.*

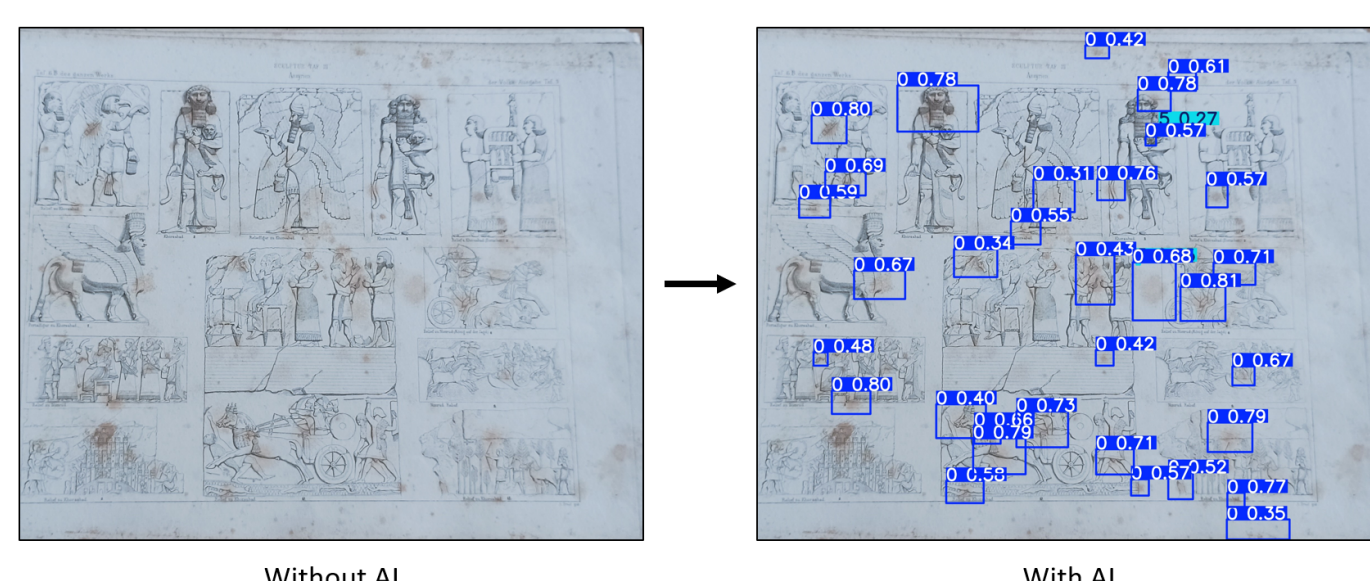


Figure 1. Without vs. with AI-assisted detection.

Example of Synthetic Data

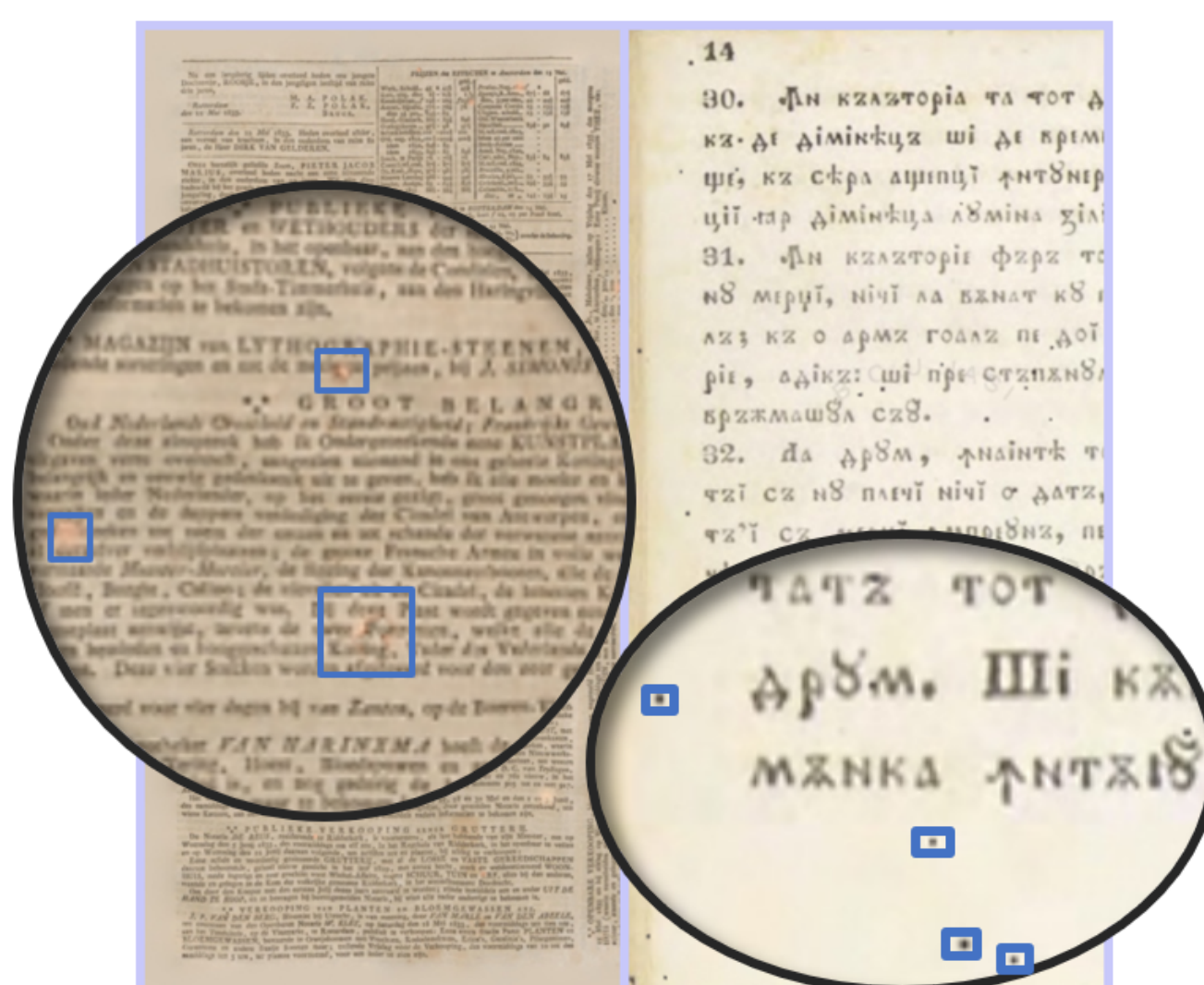


Figure 3. Example of syn. data classes foxing and feces.

Visual Results – YOLOv8s

Comparison of predictions from models trained on different datasets:

- Green – Ground Truth.
- Blue – Combined dataset.
- Violet – Synthetic dataset.
- Yellow – Real dataset.

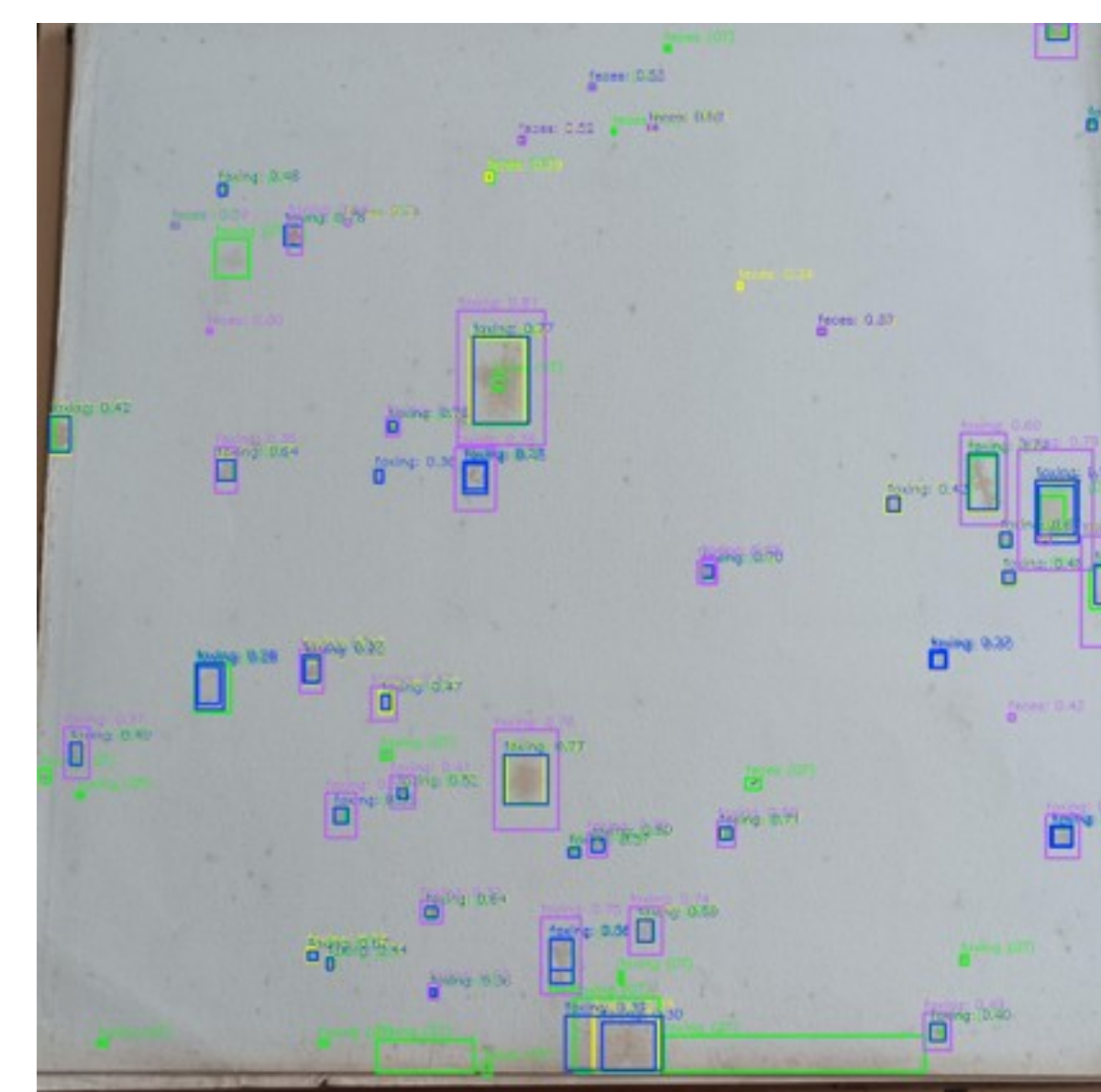


Figure 5. Visual comparison of predictions across dataset variants (YOLOv8s model).

Real Dataset

Semi-automatic annotation.
218 annotated images, 11 387 bounding boxes.

- Automated preprocessing using HSV thresholding – initial BBs.
- Manual correction – *Roboflow*.

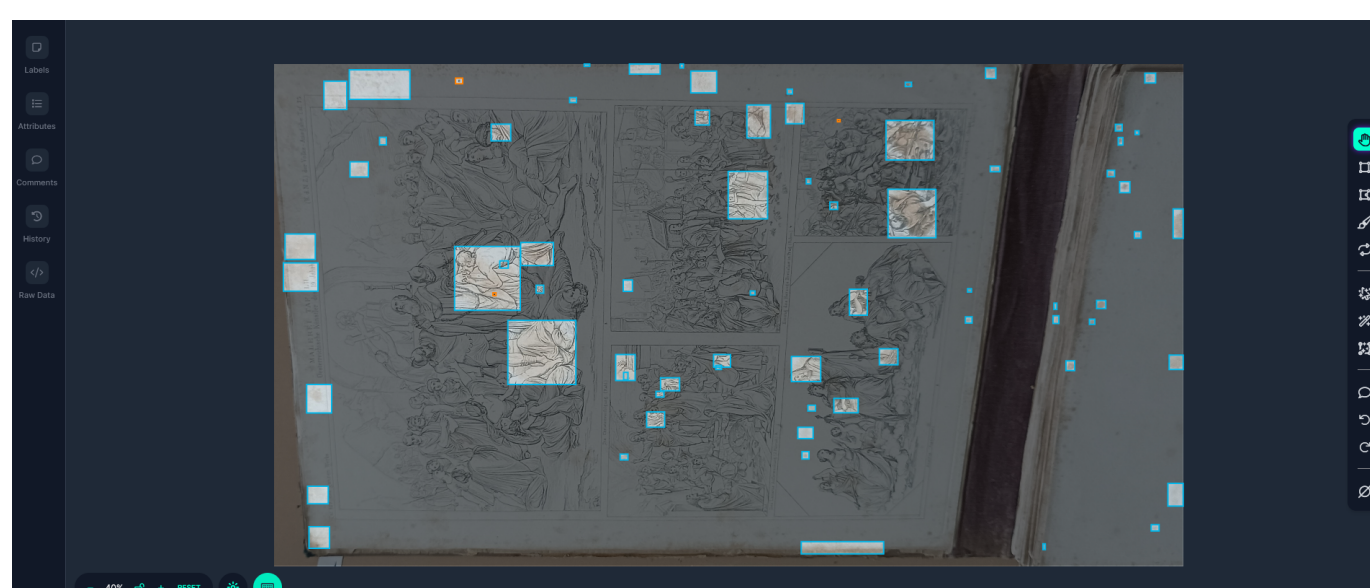


Figure 2. Example of annotation process in Roboflow.

Results

YOLOv8 architectures: n , s , m , s_param .

- 3 dataset variants:
 - Synthetic dataset.
 - Real dataset.
 - Combined dataset.
- Evaluation metrics: Precision, Recall, mAP@50, mAP@50–95.

Dataset	Precision	Recall	mAP@50	mAP@50-95
Synthetic	0.117	0.132	0.0597	0.0137
Real	0.386	0.343	0.297	0.101
Combined	0.323	0.316	0.2690	0.0897

Table 1. Best model results across datasets.

Future Work

- Expand real dataset.
- Explore various synthetic data generation methods (*GANs*, *style transfer*).
- Generate and analyze artificially aged or damaged documents to simulate real deterioration.
- Test advanced architectures: *Faster R-CNN*, *RT-DETR*, *EfficientDet*.

Synthetic Dataset

- 651 images, 2 classes (*foxing*, *feces*)
- Stains extracted using SAM
- Generated on undamaged papers

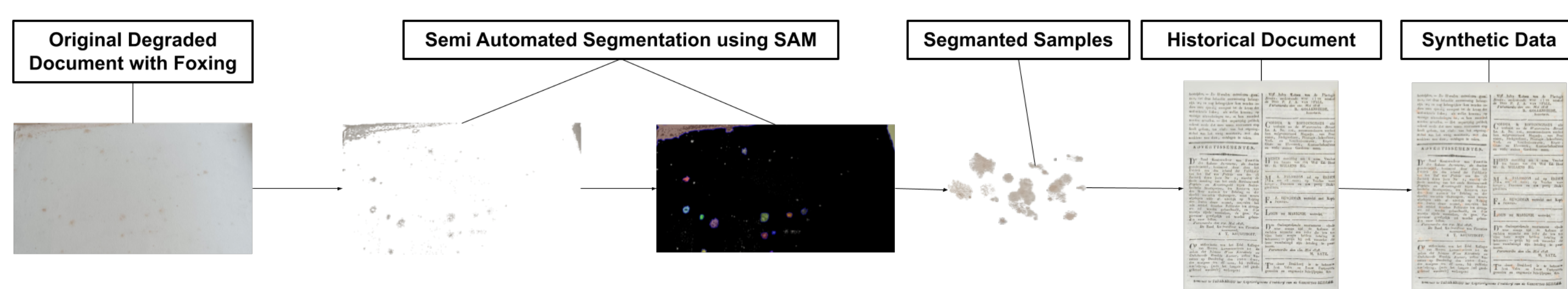


Figure 4. Workflow for generating synthetic data.

References

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- Joseph Redmon, Santosh Divvala, Ross Girshick, and Ali Farhadi. You only look once: Unified, real-time object detection. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pages 779–788, 2016.

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